

Evidential Deep Learning for Uncertainty-Aware Mobile Health

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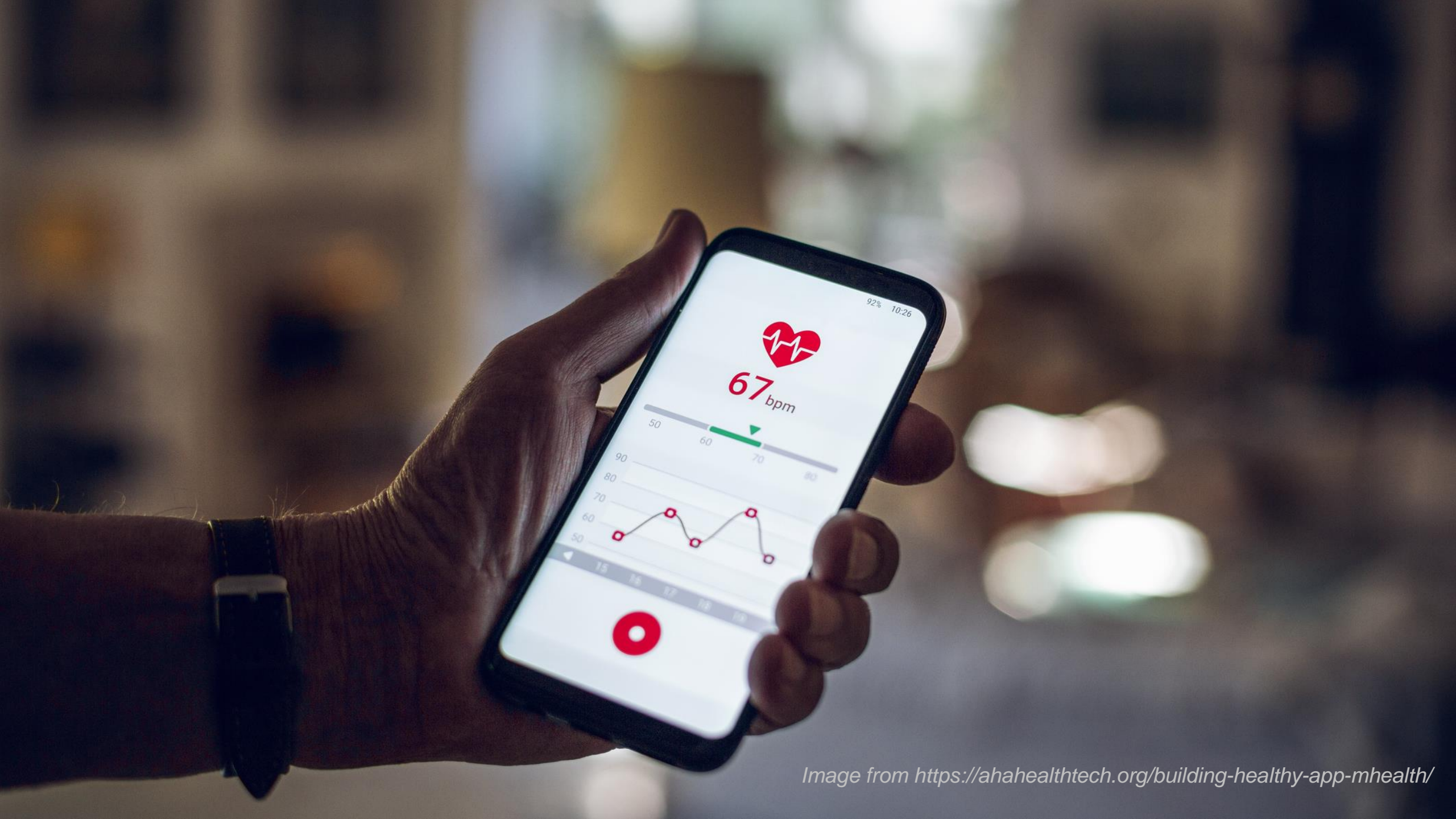
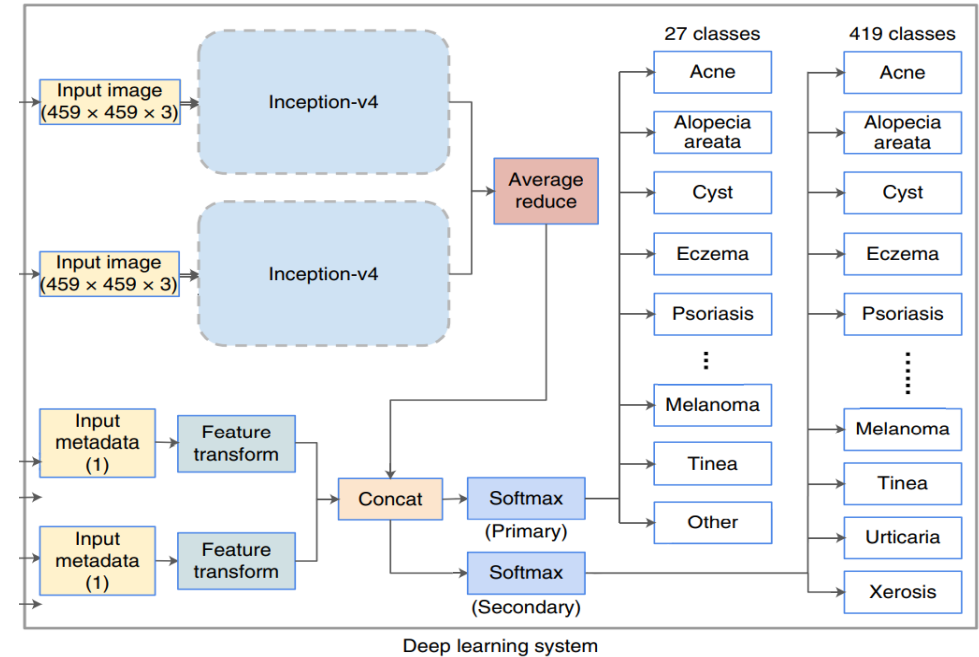
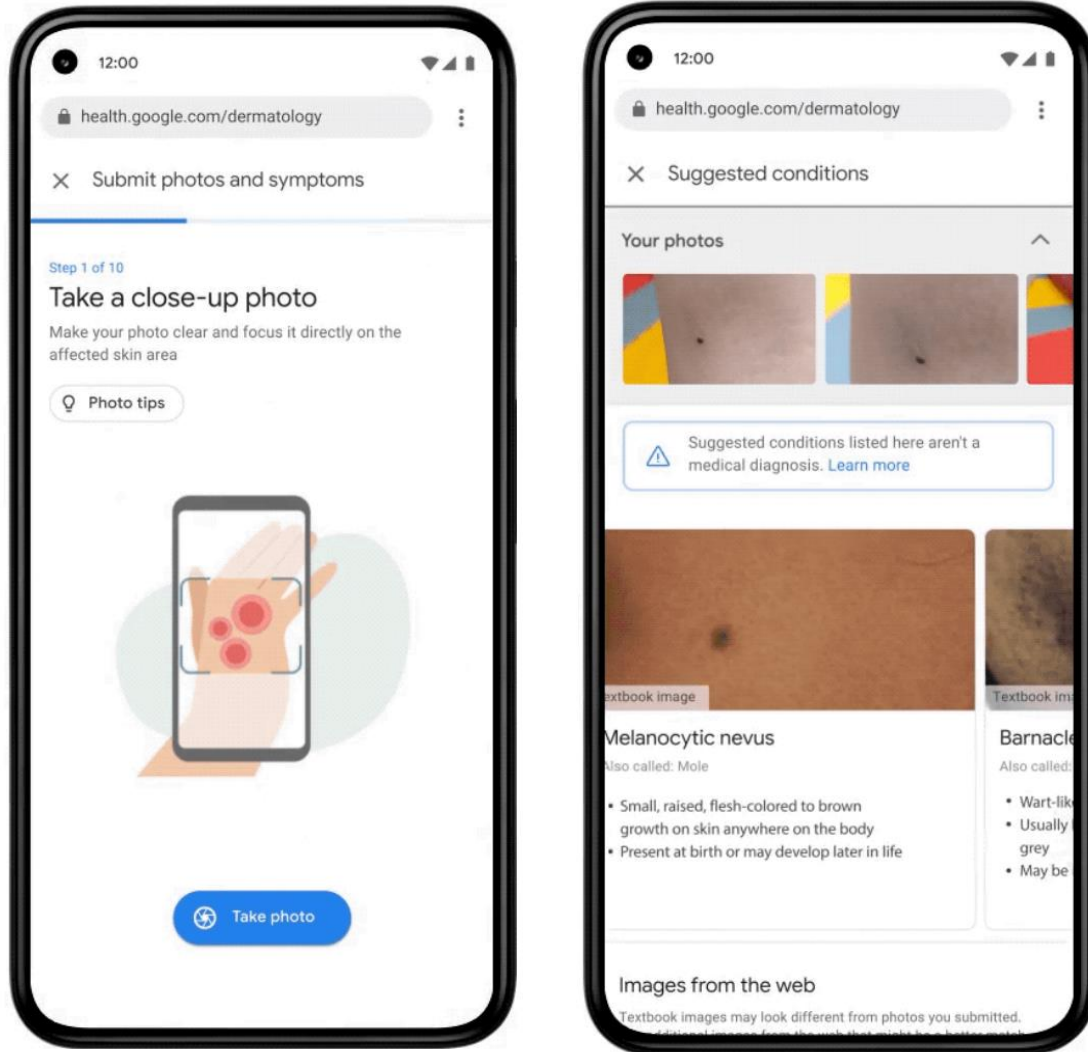


Image from <https://ahahealthtech.org/building-healthy-app-mhealth/>

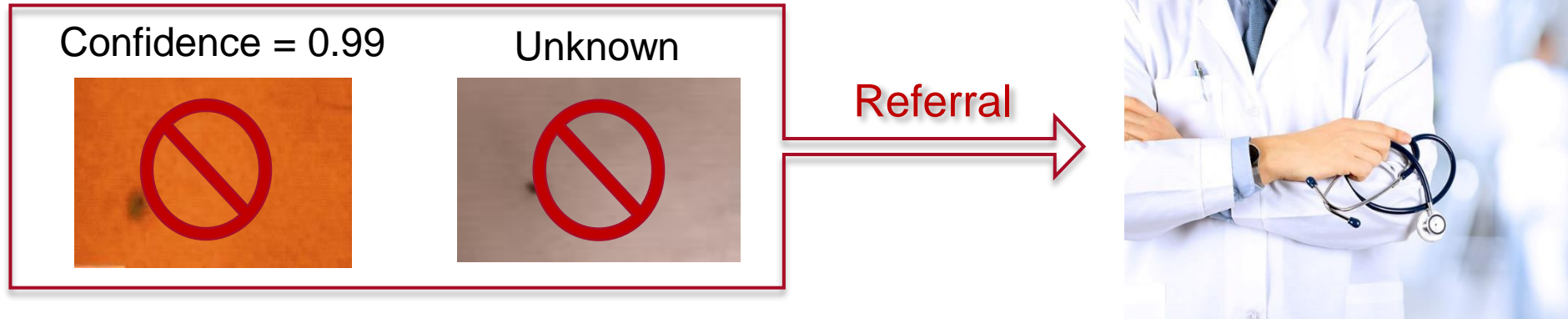
Google AI-powered Dermatology Tool



Misdiagnosis Risk:

- Unexpected environment/lighting
- Difference among cameras
- Uncommon skin condition
- ...

Why uncertainty is important for mHealth



Uncertainty Quantification for Health:

- **Calibration**: the confidence of prediction associated with a trained condition
- **OOD aware**: the likelihood of an input belonging to the out-of-distribution regime of training data
- **Low cost**: no extra inference cost, no extra training data required

Evidential Deep Learning (EDL) for Uncertainty Quantification

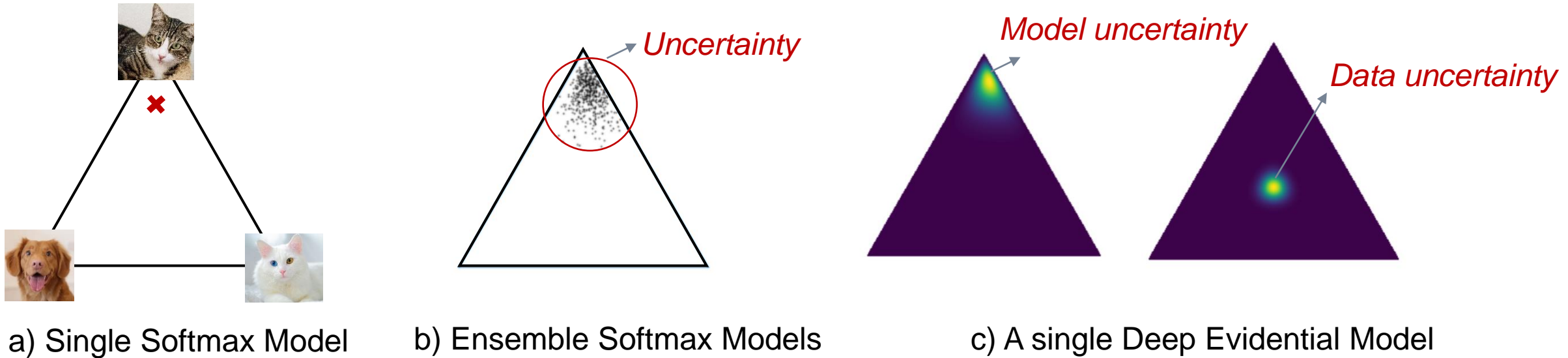


Figure 1: 3-classification problem. Brighter colors correspond to higher density.

Evidential Deep Learning (EDL) for Uncertainty Quantification

□ A Dirichlet distribution $Dir(\alpha)$ is parameterised by a group of concentrations denoted by $\alpha = [\alpha_1, \alpha_2, \dots, \alpha_k]$, corresponding to a k -class categorical problem.

- Predictive probability:

$$\mathbb{E}[p_c] = \frac{\alpha_c}{\alpha_0},$$

- Prediction:

$$\hat{y}^{(i)} = \arg \max_c \mathbb{E}[p_c^{(i)}],$$

- Uncertainty:

$$DE = \mathbb{E}_{p \sim Dir(\alpha \cdot \omega)} [-\ln(p)]$$

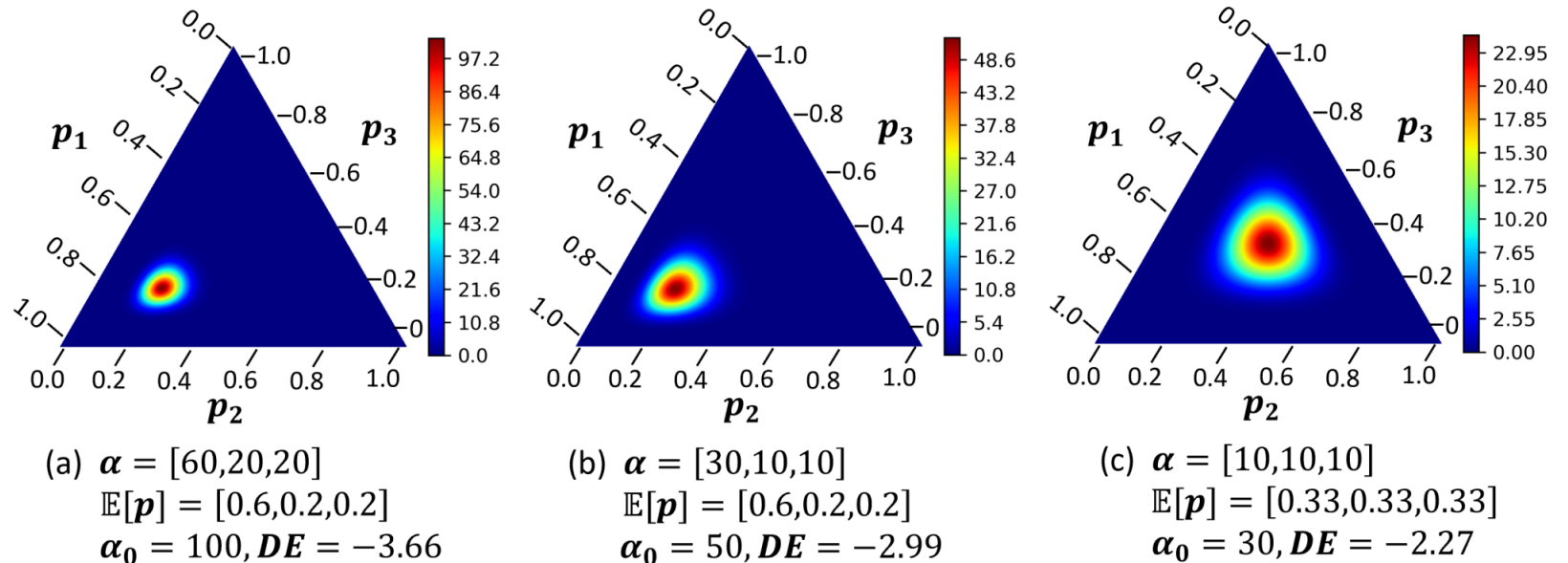


Figure 2: Dirichlet probability density functions for a three class setting.

An EDL Framework for mHealth with class imbalance

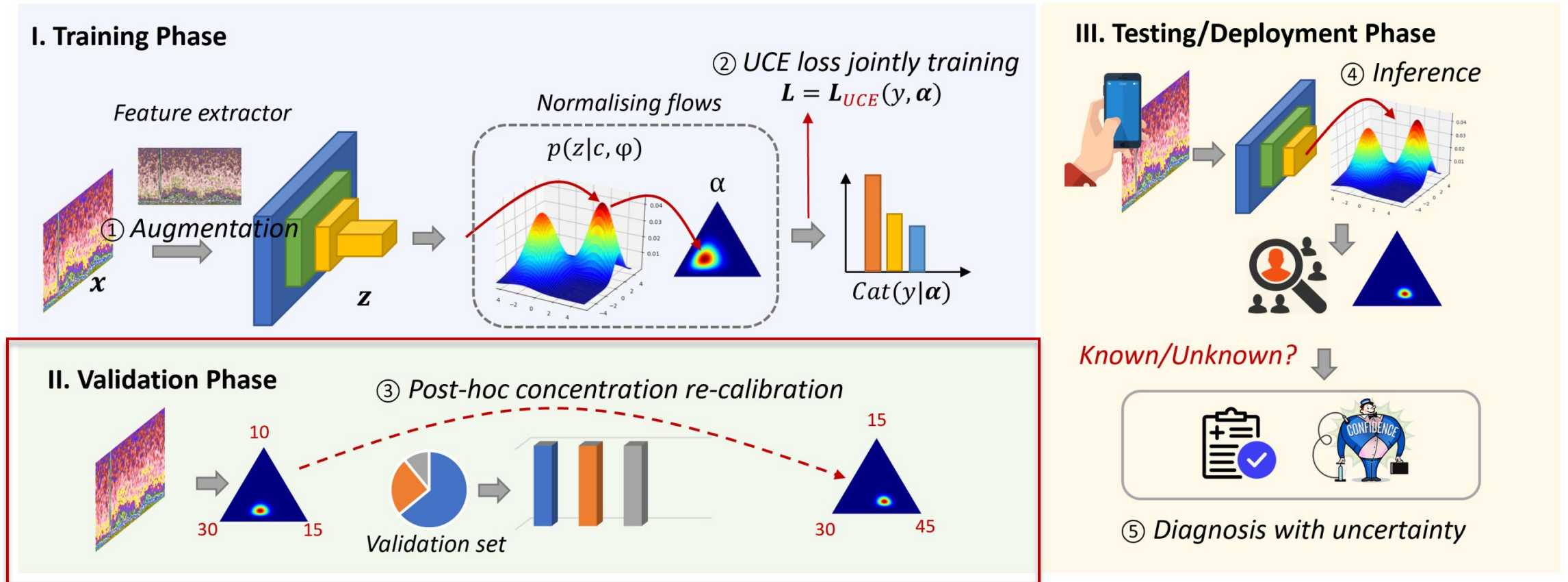


Figure 3: Our framework trains the model with an uncertainty-loss and **re-calibrates the model according to the validation data distribution to eliminate the data imbalance bias**. At deployment stage, the qualified uncertainty allows the model to recognise unconfident diagnosis and out-of-distribution input.

Experiments on Real-world Health Data

Table 1: A summary of tasks and datasets for experiments. #Train is the original data size before augmentation, and it is further split into training and validation folds for five-fold cross-validation. C is the number of classes and D is input data dimension. All experiments are implemented by Pytorch, and * denotes that pre-trained checkpoints were used for model initialisation.

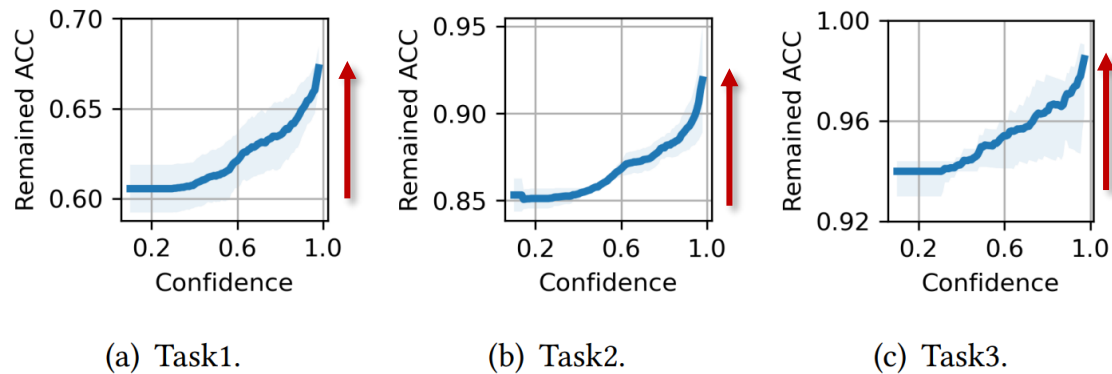
Task			IID Dataset				OOD Dataset				
Name	Backbone	Modality	Name	#Train	#Test	C	D	Name	Size	Name	Size
#1 Respiratory	ResNet-34*	Audio	ICBHI2017	4,274	2,641	4	1×32,000	Stethoscope	336	ARCA23K	2,264
#2 Skin	DenseNet-121*	Image	HAM10000	7,206	2,809	7	3×600×450	ISIC2017	1,824	CIFAR-10	10,000
#3 Heart	FCNet	ECG	EGC5000	4,500	500	5	1×140	ECG200	200	FetalECG	1,965

□ RQ 1: Diagnosis accuracy (particular for the minority classes)

	Task 1						Task 2						Task 3					
	ACC↑	UAR↑	SE↑	NLL↓	Brier↓	ECE↓	ACC↑	UAR↑	SE↑	NLL↓	Brier↓	ECE↓	ACC↑	UAR↑	SE↑	NLL↓	Brier↓	ECE↓
DirichNet	0.610 (.014)	0.442 (.006)	0.531 (.018)	1.508 (.185)	0.642 (.029)	0.284 (.031)	0.855 (.011)	0.750 (.029)	0.860 (.040)	0.593 (.010)	0.220 (.015)	0.103 (.006)	0.940 (.007)	0.743 (.025)	1.000 (.000)	0.252 (.043)	0.115 (.016)	0.059 (.017)
Δ	0.2%	2.6%	8.4%	35.1%	3.0%	11.5%	-2.1%	1.5%	3.0%	6.9%	-2.3%	-1.0%	0.2%	2.1%	0.3%	10.0%	5.7%	4.8%

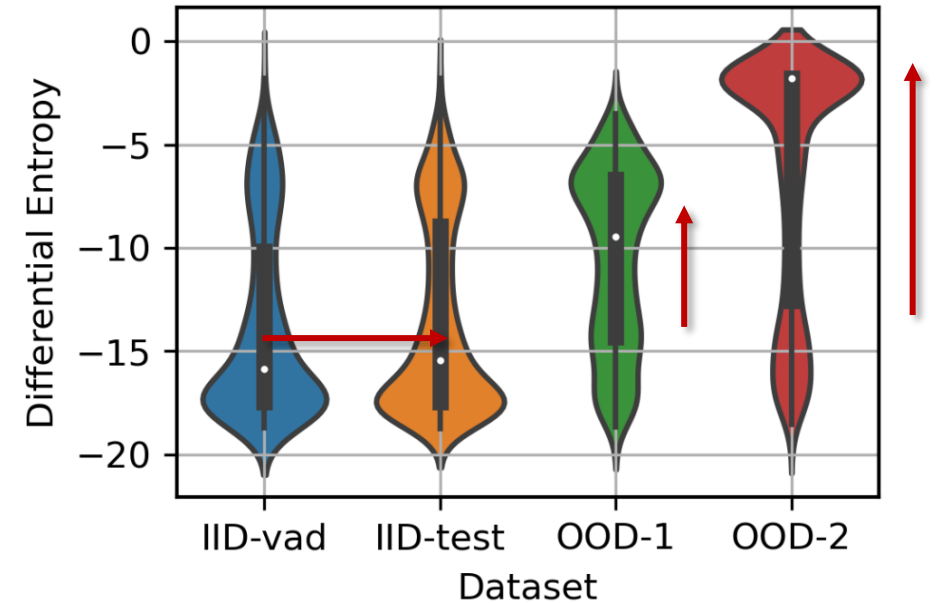
Experiments on Real-world Health Data

❑ RQ 2: Diagnostic confidence



Performance of selective prediction: After rejecting the predictions with the estimated confidence below a threshold, the diagnosis accuracy can be significantly boosted.

❑ RQ 3: Detecting Out-of-distribution Inputs



Uncertainty for IN and OOD sets

Conclusion

- ❑ In this work, we explore **evidential deep learning** for uncertainty-aware mHealth diagnostic applications from multiple clinical data modalities. EDL presents its advantage of efficiency and effectiveness.
- ❑ With our **novel re-calibration approach**, the proposed framework shows superior performance in calibrating the predictive confidence and detecting dataset shifts in the presence of imbalanced multi-class health data.
- ❑ Our findings have the potential of playing an important role in **facilitating the deployment of mobile health diagnosis models** in real-world settings, with a more transparent misdiagnosis risk management mechanism.

Thank You!

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Welcome to chat with me: tx229@cam.ac.uk



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An EDL Framework for mHealth with class imbalance

following the Bayesian update,

$$\alpha_c = \alpha_c^{prior} + N_c \cdot \mathbb{P}(z^{(i)} | c; \phi), \quad (2)$$

where $\alpha_c^{prior} = 1$, and $\mathbb{P}(z^{(i)} | c; \phi)$ presents the likelihood of observing $z^{(i)}$. More specifically, $z^{(i)}$ is the latent feature for sample i yielded by the feature extractor $f(\theta)$, and ϕ denotes the parameters of normalising flows. The assumption here is: *if the feature extractor $f(\theta)$ brings no additional evidence from sample i for class c , the posterior α_c will approach 1.*

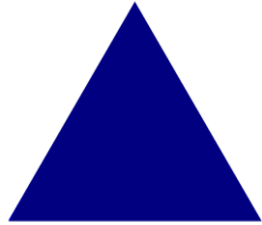


Fig. 1 step ③. Corresponding to $\alpha = [\alpha_1, \dots, \alpha_c, \dots, \alpha_K]$, we aim to seek a group of weights $\omega = [\omega_1, \dots, \omega_c, \dots, \omega_K]$ that can eliminate the classification bias, and improve the accuracy for the minority classes, particularly. Let N_c denote the number of samples of class c in the validation set. For ease of notation, we term α_1 as the concentration for the majority class $c = 1$ (the class with the largest number of training samples before data augmentation), and we let $\omega_1 = 1$. For ω_c ($c > 1, N_1 > N_c$), a fine grid search will be conducted to find a value in $[1, \frac{N_1}{N_c})$ to maximise the *unweighted average recall* (UAR) [54] on the validation set by taking the prediction from $\alpha \cdot \omega = [\alpha_1 \omega_1, \dots, \alpha_c \omega_c, \dots]$. We do not use the overall accuracy as

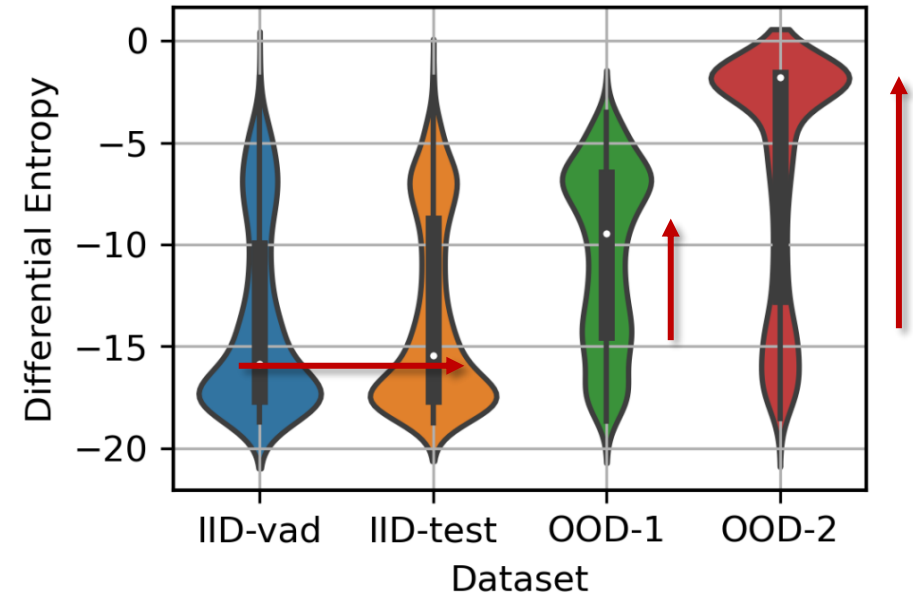
Due to the data imbalance, data augmentation also needs to be implemented to increase the size of minority classes, as shown in step ① in Fig. 1. Finally, on the balanced data, θ and ϕ can be jointly optimised (Fig. 1 ②) via the uncertainty-aware cross-entropy (UCE) loss formulated as below [13],

$$\min_{\theta, \phi} \mathcal{L} = \min_{\theta, \phi} \frac{1}{N} \sum_i \mathbb{E}_{q(p^{(i)})} [CE(p^{(i)}, y^{(i)})] - \lambda \cdot H(q^{(i)}), \quad (3)$$

Experiments on Real-world Health Data

□ RQ 3: Detecting Out-of-distribution Inputs

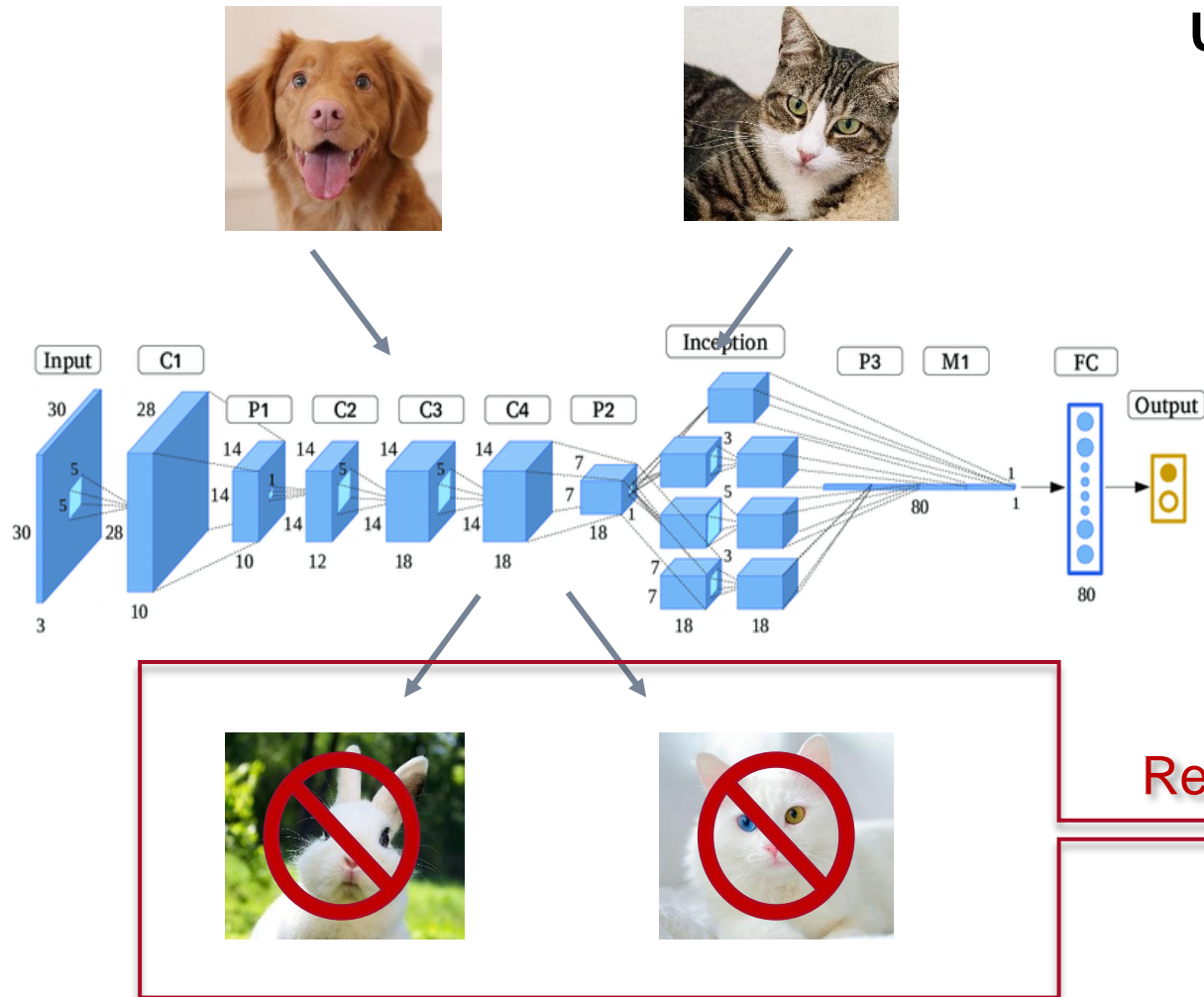
Task	OOD datasets	<i>DirichNet (ours)</i>		
		α_0	DE	Δ
#1	OOD 1 (Near)	0.731(.087)	0.733(.085)	13.8%
	OOD 2 (Far)	0.830(.156)	0.832(.151)	23.8%
#2	OOD 1 (Near)	0.740(.096)	0.744(.095)	1.1%
	OOD 2 (Far)	0.990(.008)	0.989(.007)	0.6%
#3	OOD 1 (Near)	0.788(.071)	0.816(.071)	8.1%
	OOD 2 (Far)	0.951(.029)	0.958(.021)	7.2%



(a) Task 1.

Figure 5: Performance of OOD detection.

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